Project acronym	B4B
Project full name	Brains for Building's Energy Systems
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#### Use case Chesswise

### Engineering of a new concept room ceiling sensor

Authors	Siebren de Vries
Workpackage(s)	1
Results	2
Due Date	24 April 2025
Deliverable Status	Final



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### Table of contents

- 1. Starting point for the new room sensor
- 2. Testing at Kropman Living Lab: activities and outcomes
- 3. Business results: use of outcomes in the company's market activities

# 1. Starting point: a new ceiling sensor (1)

- Talking to customers, we recognised the definition of a new room sensor that combines the most wanted functions in one box, but foremost would be invisible (no bulb on the ceiling) and prevent additional sensors or boxes on the walls.
- This wall argument is based on costs. Adding cabling to the walls is not only expensive at the start, but becomes increasingly expensive when walls are moved around in a later stage of the building's life.
- The challenge is the accurate measurement of room temperature from the ceiling. Later on, a second challenge was defined with the accurate measurement of the occupancy in rooms. Occupancy is important for climate control: the amount of fresh air is directly related to the number of people occupying the space. More generally, active climate control is necessary when people are working in a room/space. Less so, when the room/space is empty.
- For the two functions, an InfraRed 64 pixel camera is used. The design of the product and its embedded software was done just before the start of B4B.

# 1. Starting point: Engineering/validating the new ceiling sensor (2)

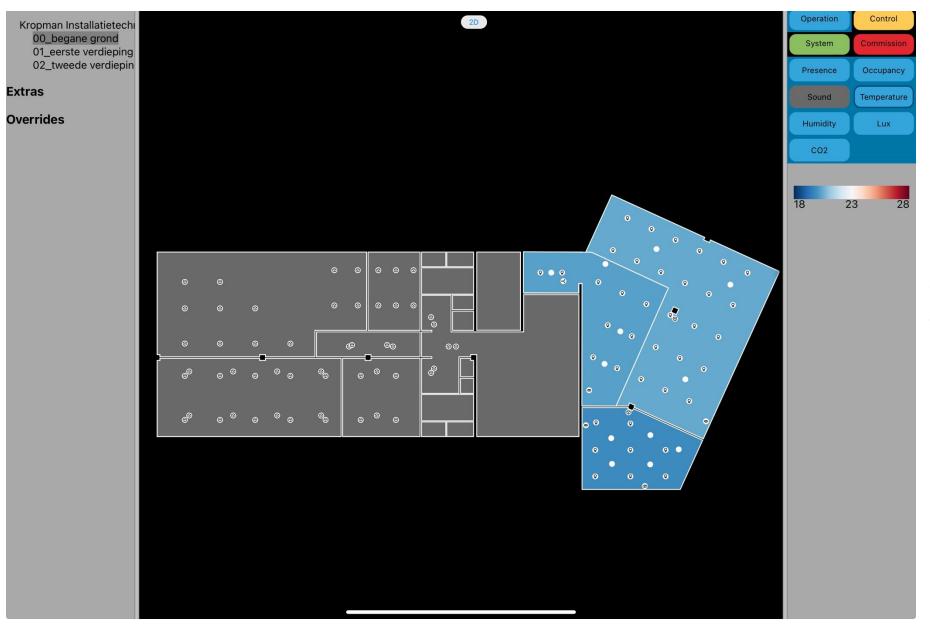
- Engineer and validate a building sensor mounted as part of the <u>room ceiling</u>. The sensor communicates in the Mymesh wireless network, and via a gateway, it makes all measured data available in the cloud for different users. This sensor provides data concerning the presence/absence of people, occupancy (number of people), room temperature, room humidity, lux light level and sound level.
- The sensor was tested for room temperature measurement within the TU/e climate room as part of another project. The sensor is designed as part of the local (lighting/climate) control loop within the distributed wireless network, allowing the real-time actual values and set points to be available in the network and the cloud.
- The <u>outcome</u> showed the necessity of calibrating the IR camera against a black body. Without this
  calibration, the measurement accurately follows the room temperature but with a fixed offset. After
  proper sensor calibration, the result is an accurate temperature sensor (within 0.2° of the test system
  within the measured range) that looks down from the ceiling. The 64 pixel thermopile brings a precise
  result and is far less influenced by air streams and change of location than classical wall thermostats.
- Combining multiple sensors in a space allows one to average or sum the measured entities. This function of adding/averaging is part of the Mymesh network functionality. The average temperature of 2, 4 or more sensors represents a very accurate room temperature reading.

# 2. Field testing in the Kropman living lab (1)

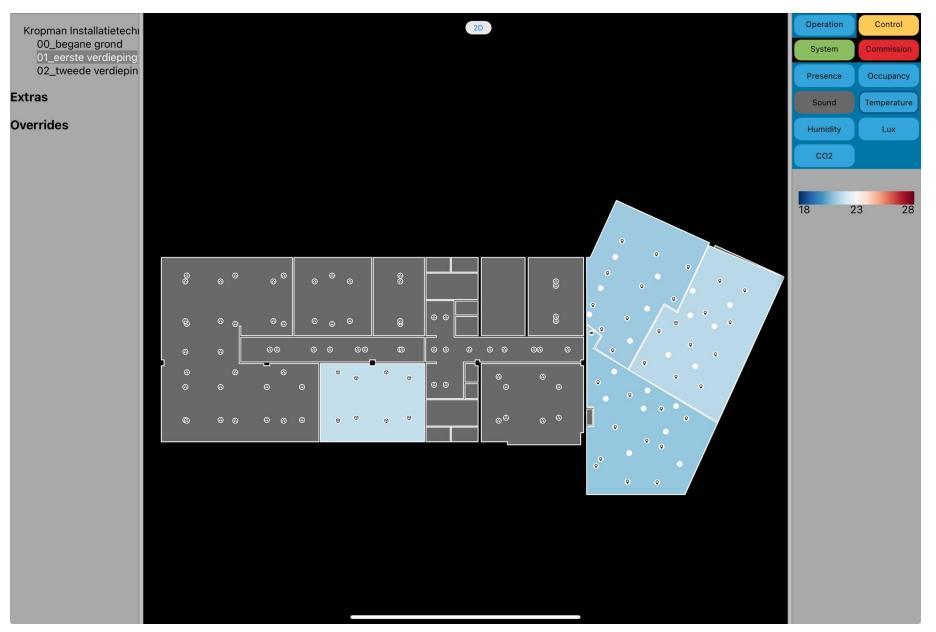
- As part of the B4B project, 32 sensors were installed (+ commissioned) in Kropman's living lab, including making real-time data available via the cloud server to third parties.
- All the sensor data is live and historically available via a REST API call. All measurements are stored in an Influx real-time data series database and are available for use by others. This creates the basis for constant live observation of the living lab and historical analysis.
- Within Mymesh, commissioning controls the averaging or summing of measured values. If two or more sensors are combined in a room, the Mymesh network configures itself to calculate the room values. So, playing with virtual rooms in a larger space allows one to move from observing a single sensor towards a larger group of sensors.
- In the first instance, the sensors were grouped into distinct rooms, whereby the measurement result was
  presented at the room level. This did not fit nicely with the first conceptual ideas around the Al learning
  systems. Next experiments were conducted with smaller virtual rooms coupled to individual sensors. This
  generated too much frustration for the daily users of the spaces and thus was commissioned back to
  room operation with some separate control zones. These smaller virtual rooms (entities) also bring
  smaller sections in the lighting control, generating annoying effects depending on people working behind
  their desks and walking around.

# 2. Field testing in the Kropman living lab (2)

- Occupancy measurements were not precise enough. The errors were caused by double counting between sensors, not counting when the person was in between sensors (larger distance between sensors), wrong counting of hot objects (like PC's), etc.
- Next, the occupancy results were improved with a new software version. Also, three CO<sub>2</sub> sensors were
  installed and made part of the available data stream. Sound is installed but not yet activated. Soundlevel logging can be commissioned to make it available for future experiments.
- The expected correlation between occupancy and  $CO_2$  can be shown, as well as the seasonal effect on the room temperature (see slides <u>9 and 10</u>). This is important because the occupancy signal is available earlier than the  $CO_2$  high level. And thus proper ventilation can be started earlier, preventing higher concentrations of  $CO_2$ .
- The next two slides (7 and 8) show the actual temperature over the spaces on the first and second floors. This data is observed in real-time using the Mymesh tool. Of course, all these actual measurements are available in Influx as historical data.



Viewing temperature on the ground floor in 3 separate spaces



Viewing temperature on the first floor in 4 separate spaces





A view on Influx database with historical data stored.

Query over 6 month's or 26 weeks.

Upper right window is the presence detection used for light control. Clearly see all days of the week and the weeks, because the weekends there is only absence.

Left middle window is the occupancy, which shows the irregularity of the amount of visitors in this space.

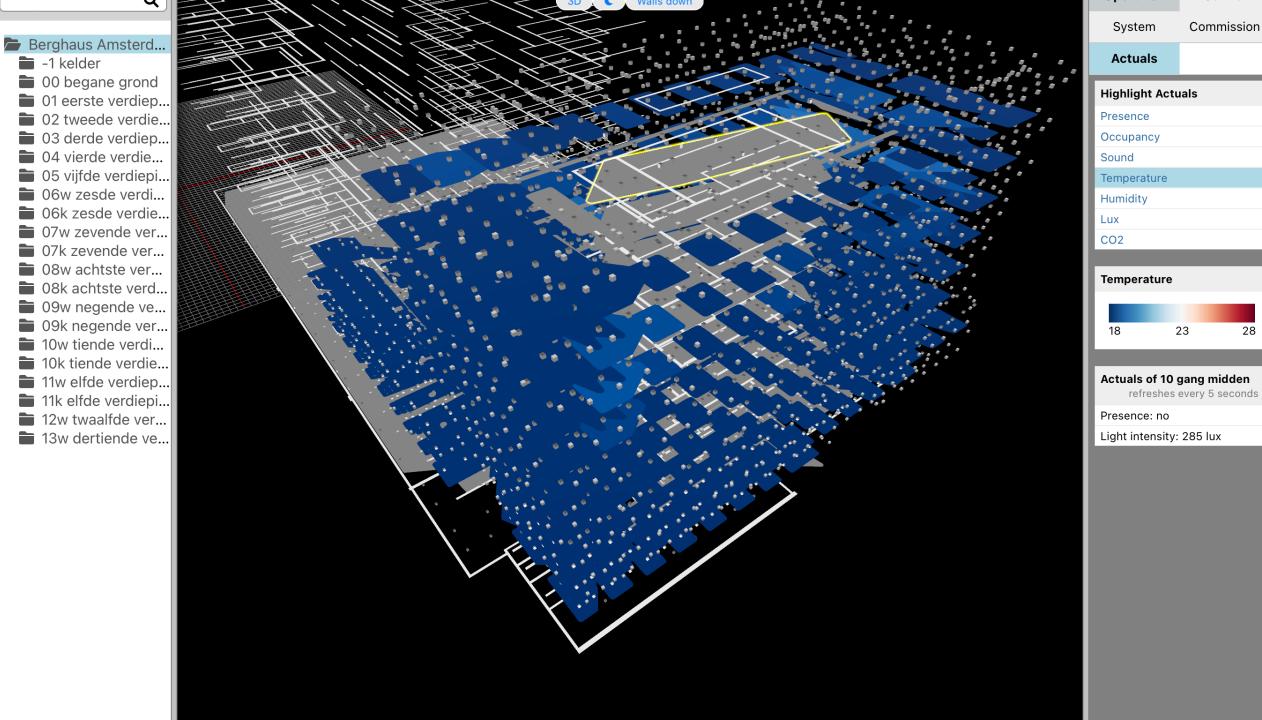
Left under the temperature over the same time window. Clear shift towards summer plus the daily swing.



When looking for the relationship between occupancy and the CO2 measurements, we observe a very clear correlation. It is obvious that the occupancy is detected earlier than the rising CO2 level.

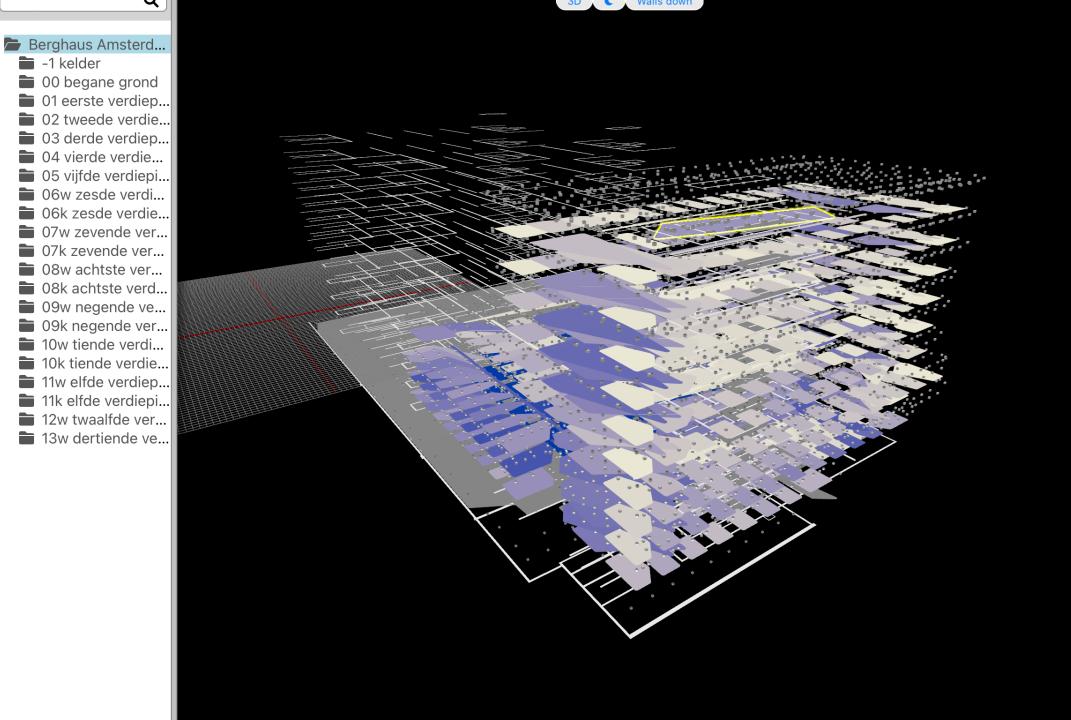
### 3. Business results

- Discovering the necessity for factory calibration of the temperature measurement. The result is now a very accurate space/room temperature measurement.
- Determined proof for the ventilation based on occupancy instead of CO<sub>2</sub>.
- A series of new projects acquired using the above results
- Improved the user interface towards an operational building. Looking at all temperatures in the whole building gives great insight into the installation.
- The next slides show an example of the larger building, completely based on this sensor. We show temperature and light level over a 13 story building in one go. A big help is finding errors in the installation.
- The next slide is a week of historical data from the office in Veldhoven. Gives great insight into the temperature behaviour of the building.
- Outside B4B scope, we added beaconing to the same product and use this for a location-based control App, allowing users to look and change the set-points of their space.
- Also based on the gathered data we no present ESG reporting, even live in the control App.
- The last two slides are two more projects. In this presentation, we used Kropman/Breda, Berghaus Plaza/Amsterdam, Simac TechniekHuijs/Veldhoven, Staalkade/Amsterdam,



Commission

28



-1 kelder

System

Commission

Actuals

#### **Highlight Actuals**

Presence

Occupancy

Sound

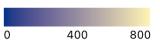
Temperature

Humidity

Lux

CO2

#### Lux



#### Actuals of 10 gang midden

refreshes every 5 seconds

Presence: no

Light intensity: 285 lux

